

Mathematics for Machine Learning

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Partial Differentiation and Gradients

Definition

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$$\begin{aligned} f'_{x_1}(\mathbf{x}) &= \frac{\partial f}{\partial x_1}(\mathbf{x}) = \lim_{h \rightarrow 0} \frac{f(x_1 + h; x_2; \dots; x_n) - f(x_1; x_2; \dots; x_n)}{h} \\ &\vdots \\ f'_{x_n}(\mathbf{x}) &= \frac{\partial f}{\partial x_n}(\mathbf{x}) = \lim_{h \rightarrow 0} \frac{f(x_1; x_2; \dots; x_n + h) - f(x_1; x_2; \dots; x_n)}{h}. \end{aligned}$$

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The row vector

$$\nabla f = \frac{df}{d\mathbf{x}} = \left[\frac{\partial f(\mathbf{x})}{\partial x_1} \quad \frac{\partial f(\mathbf{x})}{\partial x_2} \quad \dots \quad \frac{\partial f(\mathbf{x})}{\partial x_n} \right] \in \mathbb{R}^{1 \times n};$$

is called the **gradient** of f or the *Jacobian*.

Partial Differentiation and Gradients

Differentiation Rules

If the functions f and g have partial derivatives, then

$$\text{Sum Rule: } \frac{\partial}{\partial x_i} (f(\mathbf{x}) + g(\mathbf{x})) = \frac{\partial f(\mathbf{x})}{\partial x_i} + \frac{\partial g(\mathbf{x})}{\partial x_i}$$

$$\text{Product Rule: } \frac{\partial}{\partial x_i} (f(\mathbf{x}) g(\mathbf{x})) = \frac{\partial f(\mathbf{x})}{\partial x_i} g(\mathbf{x}) + f(\mathbf{x}) \frac{\partial g(\mathbf{x})}{\partial x_i}$$

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Example

Find the gradient of the following functions:

a) $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $f(x_1; x_2) = (2x_1 + 3x_2)^3$

b) $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ defined by $f(x; y; z) = e^{2x} + y^2 z^3$

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Example

Given $z(x; y) = x^2 + y^2$ where $x(r; t) = r \cos(t)$ and $y(r; t) = r + t$;

determine the value of $\frac{\partial z}{\partial t}$ and $\frac{\partial z}{\partial r}$.

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Let z be a function of two variables, $x; y$ and each of these variables $x; y$ be in turn functions of two variables, $t; s$.

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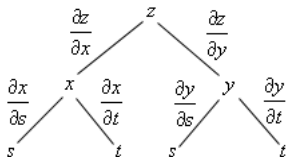
$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} = r_z \frac{\partial \mathbf{x}}{\partial s}$$

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In general, assume Z is a function of n variables, $x_1; \dots; x_n$ and each of these variables are in turn functions of m variables, $t_1; t_2; \dots; t_m$. Then for any variable $t_i; i = 1; 2; \dots; m$ we have the following,

$$\frac{\partial Z}{\partial t_i} = \frac{\partial Z}{\partial x_1} \frac{\partial x_1}{\partial t_i} + \frac{\partial Z}{\partial x_2} \frac{\partial x_2}{\partial t_i} + \dots + \frac{\partial Z}{\partial x_n} \frac{\partial x_n}{\partial t_i}$$

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Example

Find the partial derivatives $\frac{\partial z}{\partial t_i}$, $i = 1; 2; 3$ of the function $z(x; y)$ where $x = t_1 + 2t_2 + 4t_3$ and $y = t_1 + 3t_2 + 5t_3$.

Gradients of Vector-Valued Functions

Let $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a vector valued function.

Gradients of Vector-Valued Functions

Let $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a vector valued function. Then for a vector $\mathbf{x} = [x_1 \ \dots \ x_n]^T \in \mathbb{R}^n$, the value of the function \mathbf{f} at point \mathbf{x} is a *vector* given as

$$\mathbf{f}(\mathbf{x}) = \begin{bmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_m(\mathbf{x}) \end{bmatrix} \in \mathbb{R}^m$$

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Here the functions $f_j : \mathbb{R}^n \rightarrow \mathbb{R}$ are real-valued functions.

Gradients of Vector-Valued Functions

Therefore, the **partial derivative of a vector-valued function** $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ with respect to $x_i \in \mathbb{R}; i = 1; \dots; n$; is given as the vector

$$\frac{\partial \mathbf{f}}{\partial x_i} = \begin{pmatrix} \frac{\partial f_1}{\partial x_i} \\ \frac{\partial f_2}{\partial x_i} \\ \vdots \\ \frac{\partial f_m}{\partial x_i} \end{pmatrix} \in \mathbb{R}^m:$$

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Hence the **gradient of the vector-valued function** $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is

$$r f = \begin{pmatrix} \frac{\partial f}{\partial x_1} & \dots & \frac{\partial f}{\partial x_n} \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_n} \end{pmatrix} \in \mathbb{R}^{m \times n}$$

Gradients of Vector-Valued Functions

Note that gradient of the vector-valued function can also be represented as follows

$$\begin{matrix}
 \begin{matrix} 2 & 3 \\ \color{blue}{r f_1} \\ 6 & 7 \\ \vdots & \vdots \\ \color{purple}{r f_m} \end{matrix} & = & \begin{matrix} 2 & 3 \\ \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ 6 & 7 \\ \vdots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \cdots & \frac{\partial f_m}{\partial x_n} \end{matrix} & \in \mathbb{R}^{m \times n}
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Definition

The **Jacobian matrix** is the matrix of all first-order partial derivatives of a vector-valued function $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$. The Jacobian matrix \mathbf{J} of \mathbf{f} is an $m \times n$ matrix, usually defined and arranged as follows:

$$\mathbf{J} = r \mathbf{f} = \begin{matrix} \frac{\partial \mathbf{f}}{\partial x_1} & \cdots & \frac{\partial \mathbf{f}}{\partial x_n} \\ \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{matrix}; \quad \mathbf{J}_{ij} = \frac{\partial f_i}{\partial x_j}$$

Gradients of Vector-Valued Functions

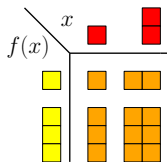


Figure: The dimension of the Jacobian J_f

Gradients of Vector-Valued Functions

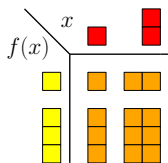


Figure: The dimension of the Jacobian J_f

In particular, the Jacobian of a function $f: \mathbb{R}^n \rightarrow \mathbb{R}^1$, which maps a vector $\mathbf{x} \in \mathbb{R}^n$ onto a scalar, is a row vector (matrix of dimension $1 \times n$).

Gradients of Vector-Valued Functions

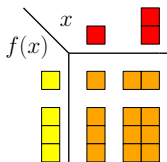


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Example

Find the Jacobian of the following functions:

- $f: \mathbb{R}^2 \rightarrow \mathbb{R}$; given by $f(\mathbf{x}) = x_1 + x_2^3$
- $\mathbf{f}: \mathbb{R}^2 \rightarrow \mathbb{R}^3$; given by $f(\mathbf{x}) = [2x_1; x_1x_2; x_1 + 3x_2]^T$

Gradients of Vector-Valued Functions

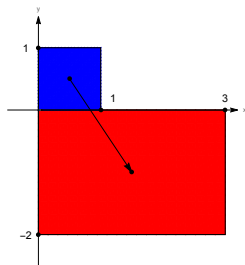
Consider the vector valued function $\mathbf{f} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by

$$\mathbf{f}(\mathbf{x}) = \mathbf{f}(x; y) = \begin{pmatrix} 3x \\ 2y \end{pmatrix} :$$

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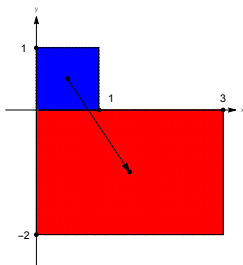
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Note that the image of the $[0; 1]^2$ (the blue square) is the rectangle $[0; 3] \times [2; 0]$ (depicted in red). The quotient of the areas of the

rectangle and the square is 6 and it is equal to $j \det \mathbf{J}_{\mathbf{f}} j = \det \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix}$

Gradients of Vector-Valued Functions

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A nonlinear map $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ sends a small square (left, in red) to a distorted parallelogram (right, in red). The Jacobian at a point gives the best linear approximation of the distorted parallelogram near that point (right, in translucent white), and the Jacobian determinant gives the ratio of the area of the approximating parallelogram to that of the original square.

Gradients of Vector-Valued Functions

Example

Find the gradient of the vector-valued function $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$; given by

$$f(x) = \begin{pmatrix} 1 & 2 & x_1 \\ 3 & 4 & x_2 \end{pmatrix} :$$

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Example

Prove that the Jacobian of the vector-valued function $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$; given by $f(x) = Ax$; where $A \in \mathbb{R}^{m \times n}$ and $x \in \mathbb{R}^n$ is

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$$J_f = A:$$

Gradients of Vector-Valued Functions

Chain Rule (Matrix form)

Let $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $f : \mathbb{R}^m \rightarrow \mathbb{R}^k$ are differentiable functions, then

$$J_{f \circ g}(\mathbf{a}) = J_f(g(\mathbf{a}))J_g(\mathbf{a}); \quad \mathbf{a} \in \mathbb{R}^n:$$

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Note that $J_{f \circ g}(a) \in \mathbb{R}^{k \times n}$; $J_f(g(a)) \in \mathbb{R}^{k \times m}$; and $J_g(a) \in \mathbb{R}^{m \times n}$:

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Equivalently, if $z = f(y)$ and $y = g(x)$ then

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Equivalently, if $z = f(y)$ and $y = g(x)$ then

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x}:$$

Example

Find the Jacobians of the functions $f \circ g$ and $g \circ f$, where $f : \mathbb{R}^2 \rightarrow \mathbb{R}$; given by $f(x) = x_1 + x_2^2$ and $g : \mathbb{R} \rightarrow \mathbb{R}^2$ given by $g(t) = \begin{pmatrix} e^t \\ t^2 \end{pmatrix}$:

Gradients of Vector-Valued Functions

Example

Using the formula $\frac{\partial x^T B x}{\partial x} = x^T (B + B^T)$ deduce that $\frac{\partial x^T x}{\partial x} = 2x^T$:

Gradients of Matrices

	Scalar Notation Type	Vector y (size m) Notation Type
Scalar x	$\frac{\partial y}{\partial x}$ scalar	$\frac{\partial y}{\partial x}$ size m col. vector
Vector x (size n)	$\frac{\partial y}{\partial x}$ size n row vector	$\frac{\partial y}{\partial x}$ $m \times n$ matrix
Matrix X (size $p \times q$)	$\frac{\partial y}{\partial X}$ $p \times q$ matrix	$\frac{\partial y}{\partial X}$ $m \times (p \times q)$ tensor

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Example

(Gradient of Scalars with respect to Matrices) Let

$$y = y(X) = \text{tr}(X); \text{ where } X \in \mathbb{R}^{p \times p}:$$

Find the gradient $\frac{\partial y}{\partial X}$.

Example

(Gradient of Vectors with respect to Matrices)

Let $v \in \mathbb{R}^q$ be a fixed vector and $f : \mathbb{R}^{p \times q} \rightarrow \mathbb{R}^p$ be a function given by

$$f(X) = Xv ; \text{ where } X \in \mathbb{R}^{p \times q}:$$

Find the gradient $\frac{\partial y}{\partial X}$ of the function $y = f(X)$:

Gradients of Matrices

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Scalar x	$\frac{\partial Y}{\partial x}$ $m \times k$ matrix
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Example

(Gradient of Matrices with respect to Matrices)

Let $f : \mathbb{R}^{p \times q} \rightarrow \mathbb{R}$ be a function given by

$$f(X) = X^T X; \text{ where } X \in \mathbb{R}^{p \times q}$$

Find the gradient $\frac{\partial}{\partial X}$ of the function $f(X)$:

Useful Identities for Computing Gradients

Limits of Multivariable Functions

Let $a \in \mathbb{R}^n$ and $\epsilon > 0$. Denote $B(a; \epsilon) = \{x \in \mathbb{R}^n : \|x - a\| < \epsilon\}$.

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Definition

Let $f : X \rightarrow \mathbb{R}^m$, $X \subseteq \mathbb{R}^n$, $a \in \mathbb{R}^n$ and $A \in \mathbb{R}^m$. We will say that $\lim_{x \rightarrow a} f(x) = A$ if for all $\epsilon > 0$ there exists $\delta > 0$, such that from $0 < \|x - a\| < \delta$; $x \in X$, follows that $\|f(x) - A\| < \epsilon$.

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Let $a \in \mathbb{R}^n$ and $\epsilon > 0$. Denote $B(a; \epsilon) = \{x \in \mathbb{R}^n : \|x - a\| < \epsilon\}$.

Definition

Let $f : X \rightarrow \mathbb{R}^m$, $X \subset \mathbb{R}^n$, $a \in \mathbb{R}^n$ and $A \in \mathbb{R}^m$. We will say that $\lim_{x \rightarrow a} f(x) = A$ if for all $\epsilon > 0$ there exists $\delta > 0$, such that from $0 < \|x - a\| < \delta$; $x \in X$, follows that $\|f(x) - A\| < \epsilon$.

Definition

Let $f : X \times Y \rightarrow \mathbb{R}$, $X, Y \subset \mathbb{R}$, $(x_0, y_0) \in \mathbb{R}^2$ and $A \in \mathbb{R}$. We will say that $\lim_{\substack{x \rightarrow x_0 \\ y \rightarrow y_0}} f(x, y) = A$ if for all $\epsilon > 0$ there exists $\delta > 0$, such that from $|x - x_0| < \delta$; $|y - y_0| < \delta$; $(x_0, y_0) \neq (0, 0)$; $x \in X$; $y \in Y$, follows that $|f(x, y) - A| < \epsilon$.

Limits of Multivariable Functions

Theorem

If $\lim_{\substack{x \rightarrow x_0 \\ y \rightarrow y_0}} f(x; y) = A$ and $\lim_{x \rightarrow x_0} f(x; y) = g(y)$ for all $y \in Y$, $y \neq y_0$, then

$$\lim_{y \rightarrow y_0} g(y) = \lim_{y \rightarrow y_0} \lim_{x \rightarrow x_0} f(x; y) = A:$$

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Example

$$f(x; y) = x \sin \frac{1}{y}, \quad (x_0; y_0) = (0; 0),$$

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Example

$$\begin{cases} 1 & f(x; y) = x \sin \frac{1}{y}, (x_0; y_0) = (0; 0), \\ 2 & f(x; y) = \begin{cases} 0; & \text{if } x \neq y; \\ 1; & \text{if } x = y \end{cases} ; (x_0; y_0) = (0; 0). \end{cases}$$

Differential

Let $f : X \rightarrow \mathbb{R}$, $X \subset \mathbb{R}^2$ and $(x_0; y_0)$ is an interior point of X .

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Definition

f is called differentiable at the point $(x_0; y_0)$ if there exists $A; B \in \mathbb{R}$ such that

$$f(x_0 + \Delta x; y_0 + \Delta y) = f(x_0; y_0) + A \Delta x + B \Delta y + o(\rho); \quad \rho \neq 0;$$

where $\rho = \sqrt{\Delta x^2 + \Delta y^2}$.

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Theorem

If partial derivatives of the first degree of f are continuous at $(x_0; y_0)$ then it is differentiable at $(x_0; y_0)$. The inverse is not true.

Example

$$f(x; y) = \begin{cases} x^2 \sin \frac{1}{x} & \text{if } (x; y) \neq (0; 0); \\ 0 & \text{if } (x; y) = (0; 0) \end{cases}$$

Example

$$f(x; y) = \begin{cases} x^2 \sin \frac{1}{x} & \text{if } (x; y) \notin (0; 0); \\ 0 & \text{if } (x; y) = (0; 0) \end{cases}$$

Definition

$$df(x_0; y_0) = \frac{\partial f}{\partial x}(x_0; y_0) x + \frac{\partial f}{\partial y}(x_0; y_0) y \text{ is called differential of } f.$$