

Deep Learning

Vazgen Mikayelyan

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- 1 Transformers
- 2 Dilated and Transposed Convolutions

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Despite GRUs and LSTMs, RNNs still need attention mechanism to deal with long range dependencies path length for codependent computation between states grows with sequence.

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Despite GRUs and LSTMs, RNNs still need attention mechanism to deal with long range dependencies path length for codependent computation between states grows with sequence.

But if attention gives us access to any state, maybe we don't need RNN?

Transformer

Self Attention Layer

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During the training phase, the W_q , W_k , and W_v matrices are learnt to get the query, key and value embeddings.

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This step will be performed with every word.

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If the word is not relevant to x_1 then the score will be small and the corresponding value will be reduced a factor of that score and similarly the significant words will get their values bolstered by the score.

Self Attention Layer

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Finally, the word x_1 will create a new 'value' for itself by summing up the values received. This will be the new embedding of the word.

Self Attention

$$\text{Attention}(q; K; V) = \sum_i \frac{e^{q \cdot k_i}}{\sum_j e^{q \cdot k_j}} v_i$$

where

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weight of each value is computed by an inner product of query and
corresponding key,
queries and keys have the same dimensionality, values have d_v .

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When we have multiple queries q , we stack them in a matrix Q :

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Self Attention

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$$\text{Attention}(Q; K; V) = \text{Softmax} \left(\frac{QK^T}{d_k} \right) V$$

Problem: as d_k gets large, the variance of $\frac{QK^T}{d_k}$ increases, thus some values inside the softmax gets large, hence its gradients gets small

Solution:

$$\text{Attention}(Q; K; V) = \text{Softmax} \left(\frac{QK^T}{\sqrt{d_k}} \right) V$$

Multi-Head Attention Layer

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$$\text{Multihead} = \text{Concat}(\text{head}_1; \dots; \text{head}_h) W^O$$

where

$$\text{head}_i = \text{Attention}(xW_i^Q; xW_i^K; xW_i^V)$$

$$W_i^Q \in \mathbb{R}^{d_{\text{model}} \times d_k}; W_i^K \in \mathbb{R}^{d_{\text{model}} \times d_k}; W_i^V \in \mathbb{R}^{d_{\text{model}} \times d_v}; W^O \in \mathbb{R}^{hd_v \times d_{\text{model}}}$$

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This is why the embeddings for all these are masked by multiplying with 0.

Feed-Forward Network

this part is a position free neural network, which consists of two fully connected layers with a ReLU activation in between:

$$\text{FFN}(x) = W_2 \text{ReLU}(W_1x + b_1) + b_2$$

Encoder-Decoder Architecture

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Dilated/Atrous Convolution

Definition 1

Let $F : \mathbb{Z}^2 \rightarrow \mathbb{R}$ be a discrete function. Let $\mathcal{I}_r = [-r; r] \setminus \mathbb{Z}^2$ and let $k : \mathcal{I}_r \rightarrow \mathbb{R}$ be a discrete filter of size $(2r + 1)^2$. The discrete convolution operator can be defined as

$$(F * k)(p) = \sum_{s+t=p} F(s) k(t)$$

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Definition 2

Let $F : \mathbb{Z}^2 \rightarrow \mathbb{R}$ be a discrete function. Let $r = [r; r] \in \mathbb{Z}^2$ and let $k : \mathbb{Z}^2 \rightarrow \mathbb{R}$ be a discrete filter of size $(2r + 1)^2$. The discrete-dilated convolution operator \downarrow_1 can be defined as

$$(F \downarrow_1 k)(p) = \sum_{s+lt=p} F(s) k(t)$$

Dilated/Atrous Convolution

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1D Dilated Convolution

Convolution as a Matrix Operation

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This linear operation takes the input matrix flattened as a 16-dimensional vector and produces a 4-dimensional vector that is later reshaped as the 2×2 output matrix.

Transposed Convolution (stride=0)

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Transposed Convolution (stride=1)

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